



Operating System

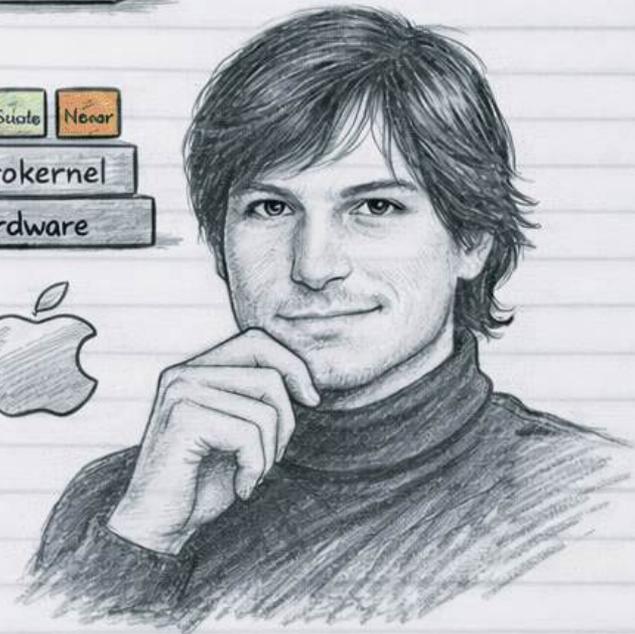
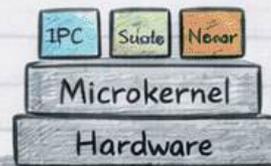
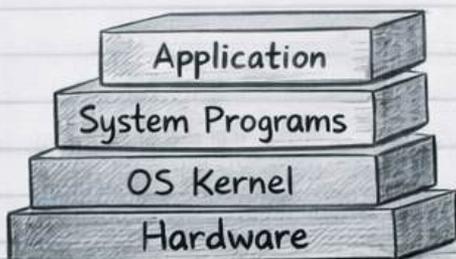
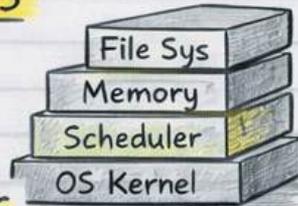
Module-1 Notes

by pyqfort.com



Contents Covered:

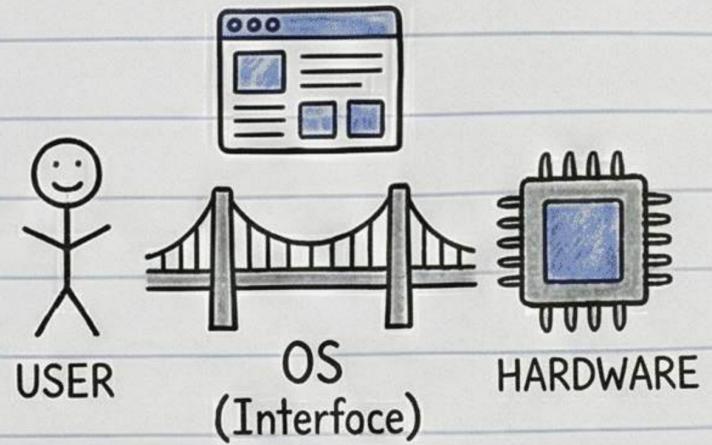
- Intro to OS 
- Types of OS 
- OS Services 
- User View & System View 
- System Calls 
- Monolithic Structure of OS
- Layered Structure of OS
- Microkernel Structure of OS



Module-1: Concept of Operating Systems

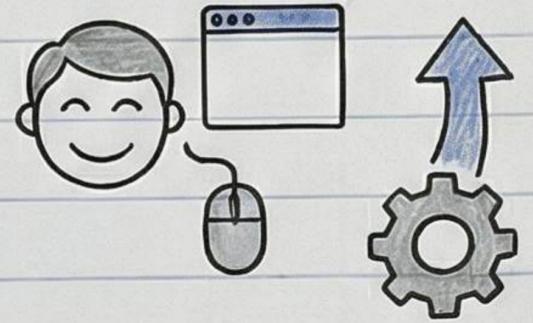
What is an OS?

- An OS is a software acting as an interface between users and hardware.
- It provides a working environment for apps and is a resource manager.



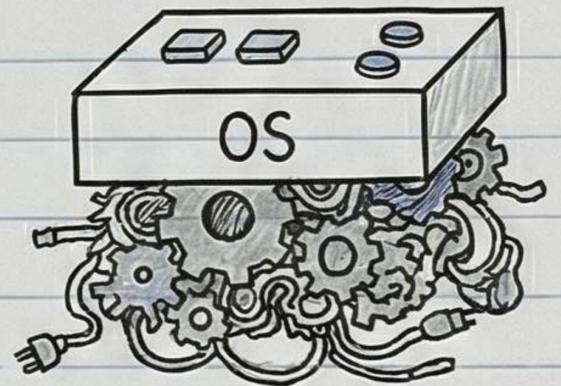
Goals of an OS:

- Prime goal is user convenience (a friendly environment, like GUI).
- Users don't want to deal with hardware details.
- Another goal is efficient utilization of hardware resources.



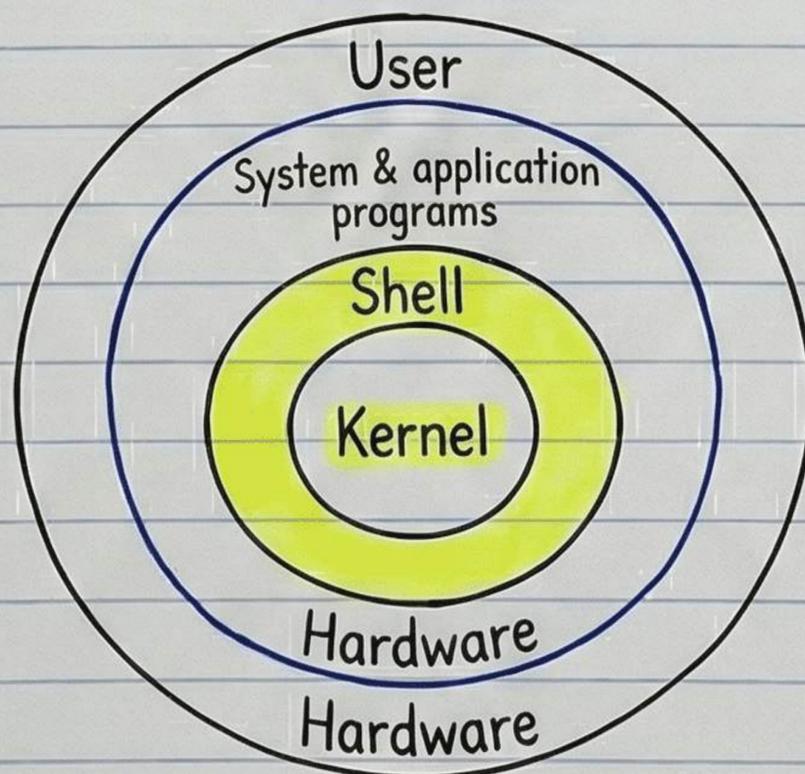
OS as an Extended Machine:

- Acts as an extended machine manager.
- It hides hardware complexity, presenting a simpler machine to the user.



Key Components & Structure:

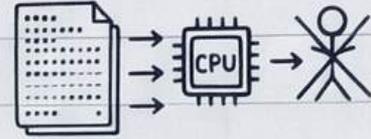
- Two generic components: Shell and Kernel.
- Shell: A command interpreter that reads user control statements.
- Kernel: Contains only the essential modules of the OS.



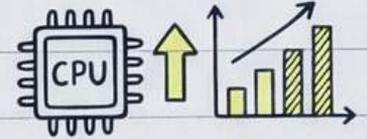
Types of Operating Systems

Batch Processing Systems

- Takes a sequence of jobs in a batch and executes them one by one without any intervention of the user.

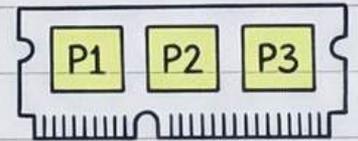


- The main advantage is to increase the CPU utilization.



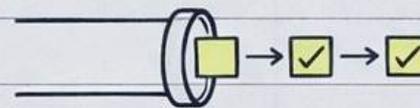
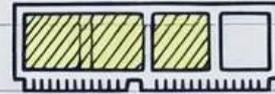
Multi-programming Systems

- A central concept: placing more than one program in the main memory.



- Major Benefits:

- * Less execution time
- * Increased utilization of memory
- * Increased throughput (jobs/time).

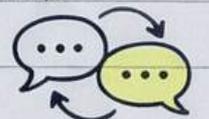
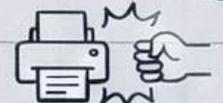


Problems & Solutions

Multi-programming originated many problems

Solutions led to new OS modules:

- Memory management (partitioning, allocation).
- Process protection (must be protected).
- Competing for limited I/O devices.
- Process communication & synchronization.

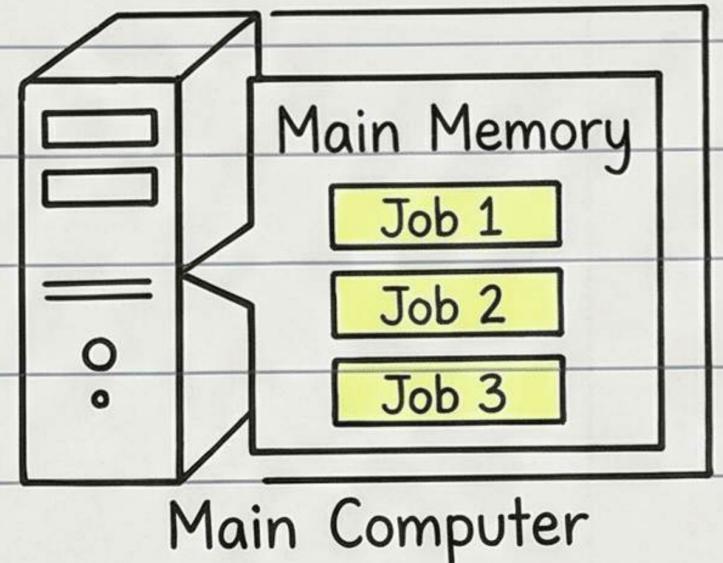


Therefore, modules like process scheduling, device management, protection, etc., were developed.

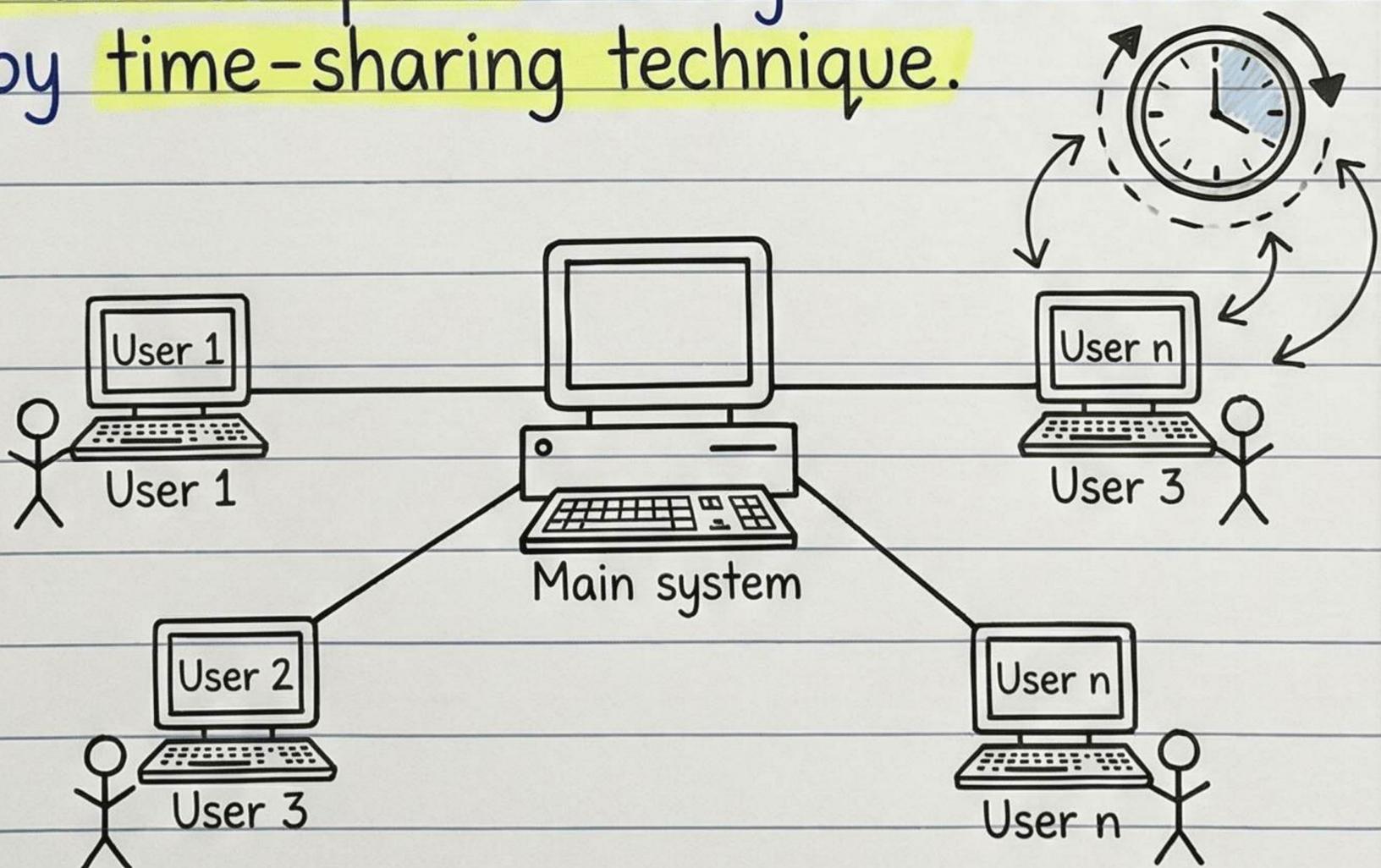


Multi-user Time-sharing Systems

- Multi-user systems place more than one job/program/task in the main memory of the main computer system.

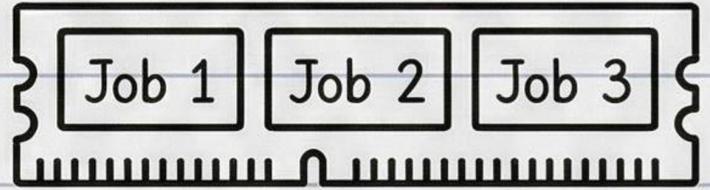


- The jobs are of different users who are connected through terminals to the main computer. The jobs are to the main computer. The jobs are scheduled by time-sharing technique.

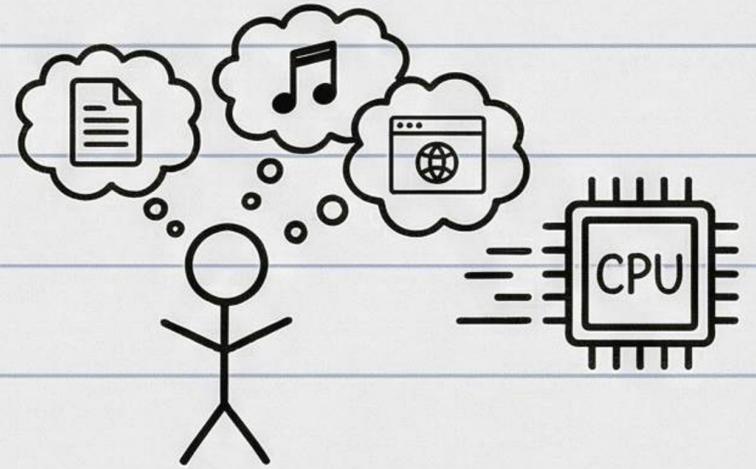


Multi-Tasking Systems

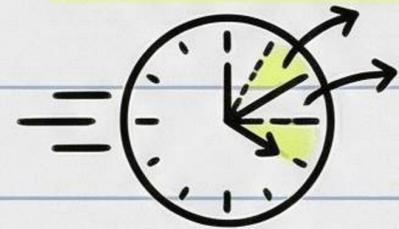
- Places more than one job/program/task. Places more than one job/program/task in the main memory.



- User gets the illusion of working in parallel on multiple tasks due to a high speed processor.



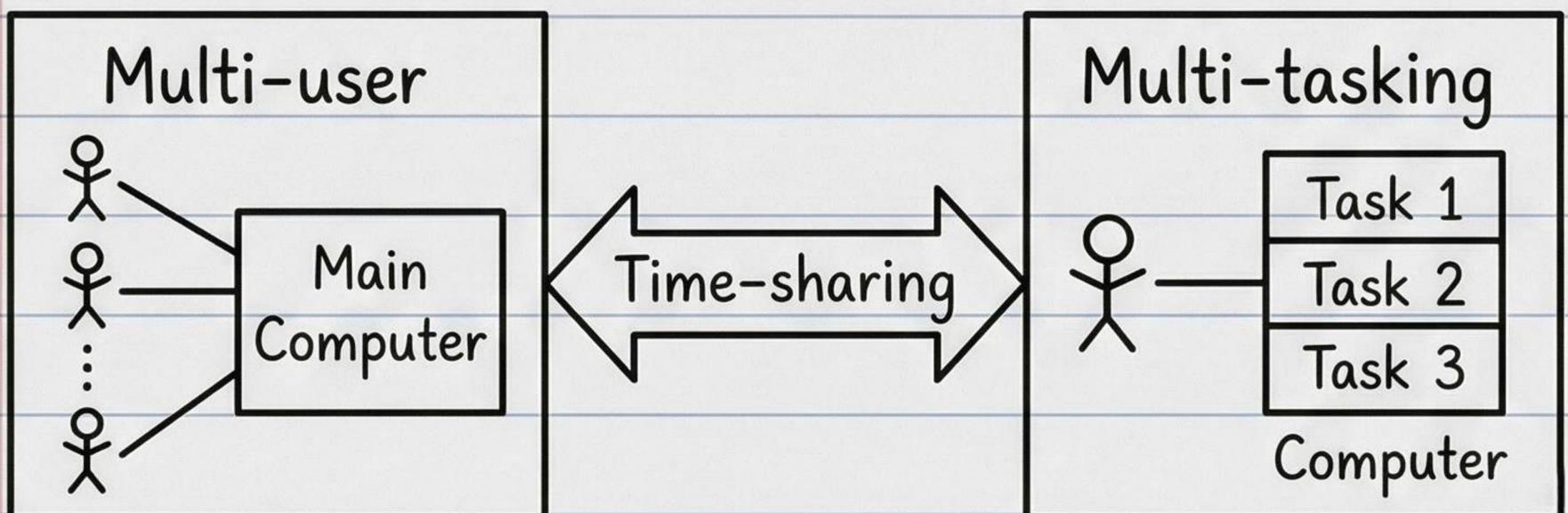
- This is made possible by the time-sharing scheduling technique.



- All jobs are from a single user.



- Multi-user and Multi-tasking are different terms, but both use time-sharing.



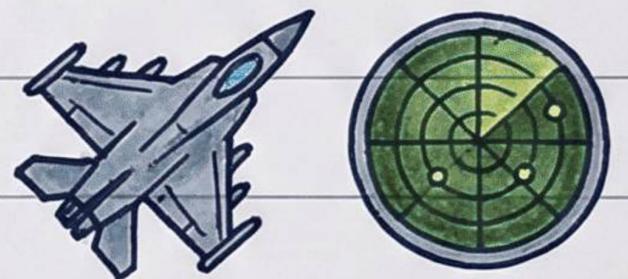
Real-Time Operating Systems (RTOS)

- Response to a user request must be **immediate** or **within a fixed time frame**, otherwise the **application will fail**.



- This is known as **real-time processing**.

- Largely useful in **defence applications** which are **mission specific**.



- If no timely response, there might be **loss of equipment** and even **life**.



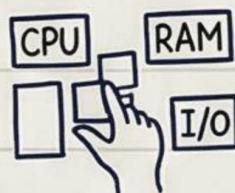
- Must meet **deadlines of time** to **prevent failures**.



OS Services

Primary Goals & Convenience

- Primary goals are **convenience** of the user and **best utilization** of hardware.
- **Convenience** is the prime goal for the user performing a job.
- **Resource Utilization/Management** : **Efficiency** is a major goal; takes care of best allocation of resources.



Abstraction & Interface

- **Hardware abstraction/virtual machine** : Provides an **abstraction layer** between user and hardware.
- **Easy-to-use interface** : Relieves user from remembering **commands** (like older UNIX/DOS).
- Provides a **convenient programming environment**.



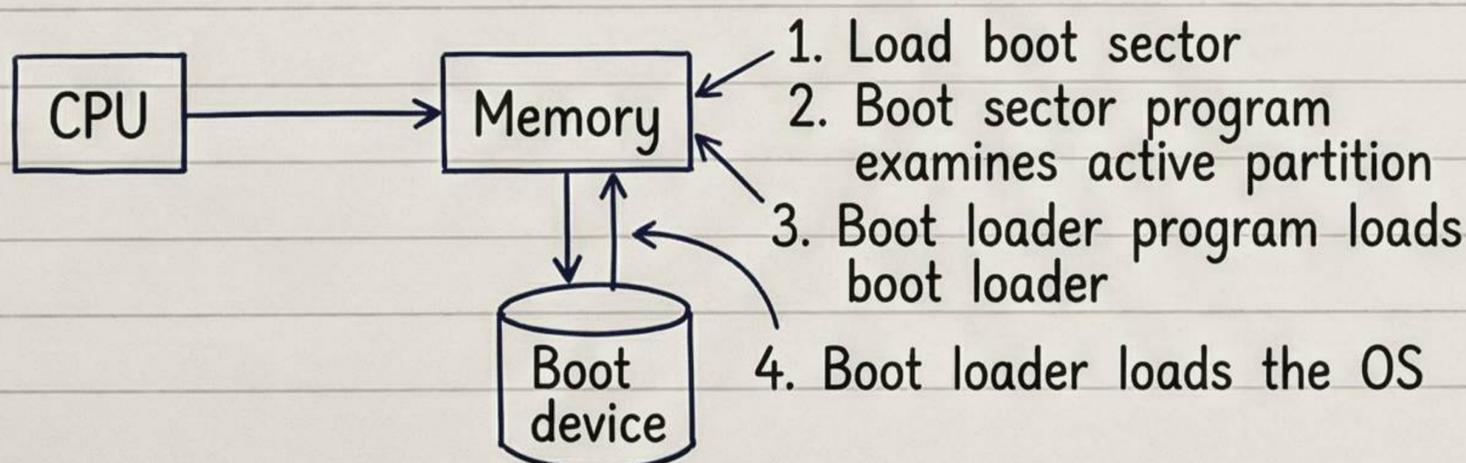
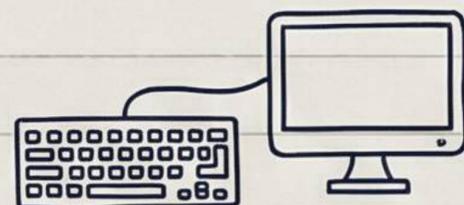
Protection & Response

- **Protection** : Protects one user's task from another and the OS from any user.
- **Response time**.



BIOS & Booting

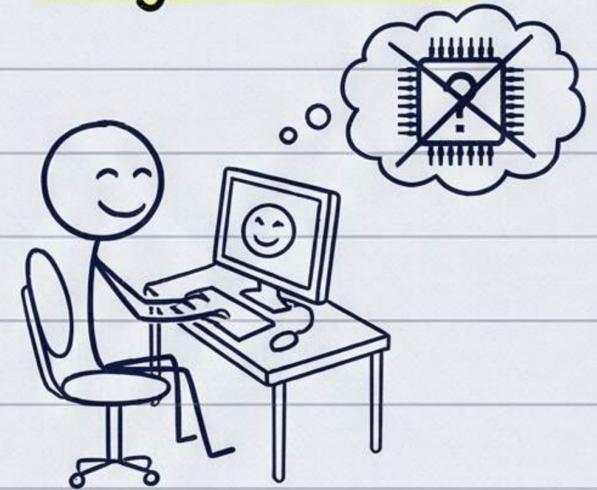
- **BIOS** : Software with low-level **I/O functions** (keyboard, screen, ports).
- **Booting** : Loading the OS into **RAM** using **Boot software/loader**.



User View & System View of OS

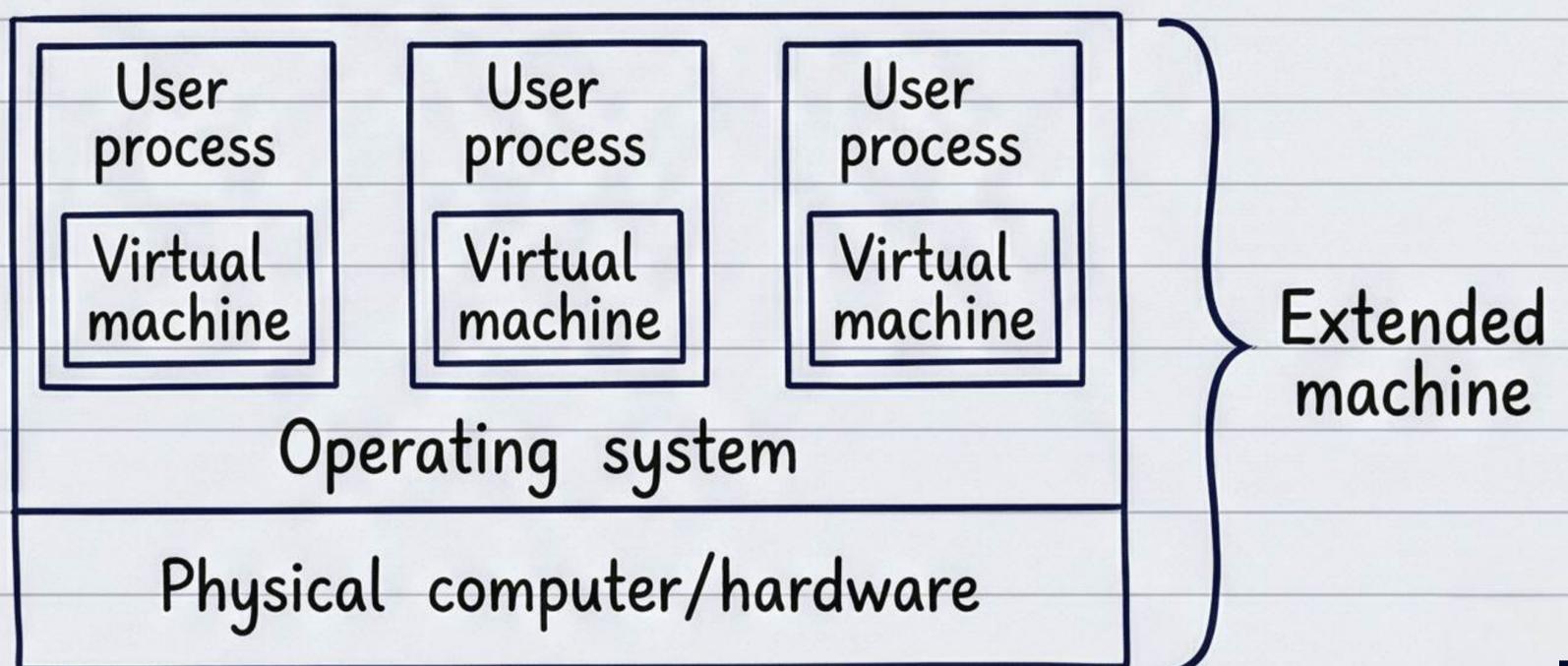
User View

- From user's viewpoint, OS acts as an **easy interface** between user & computer.
- Presents a **friendly environment** to work **efficiently**.
- User doesn't worry about **hardware details** or configuration.



System View

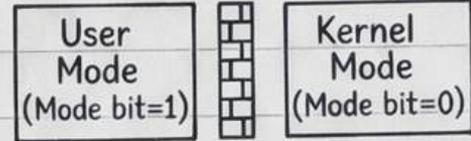
- From system's viewpoint, OS acts as a **resource manager**, **control program**, & **virtual machine manager**.
- **Resource manager**: Schedules & manages allocation of all **resources**.
- **Control program**: Controls **user activities**, I/O access, etc.
- **Virtual machine manager**: Provides an **abstraction layer** on actual hardware. Creates an **illusion** of a **virtual machine** performing the work, hiding **physical hardware**.



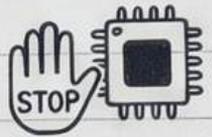
System Calls

Dual Mode & Privileged Instructions

- Modern OSs separate user code from OS code, termed **dual mode operation** : **user mode & kernel mode.**

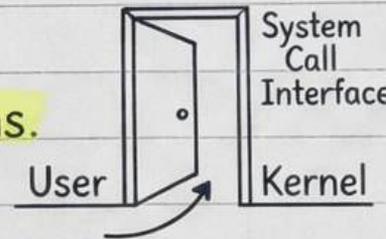


- Instructions interacting with hardware (like I/O instructions) are **privileged instructions.**
- User programs cannot directly execute them.



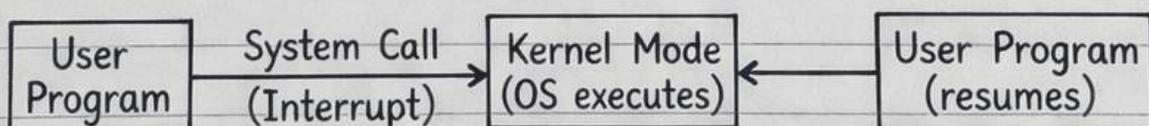
What is a System Call?

- It is the **interface** for user-mode programs to access **kernel-mode functions.**
- A **user request** to the OS to perform a task on its behalf.



How it Works

- User process makes a **system call.**
- This generates an **interrupt.**
- Interrupt changes mode to **kernel mode** (bit 0) & control passes to OS.
- OS executes the privileged instruction.
- Control returns to user mode.



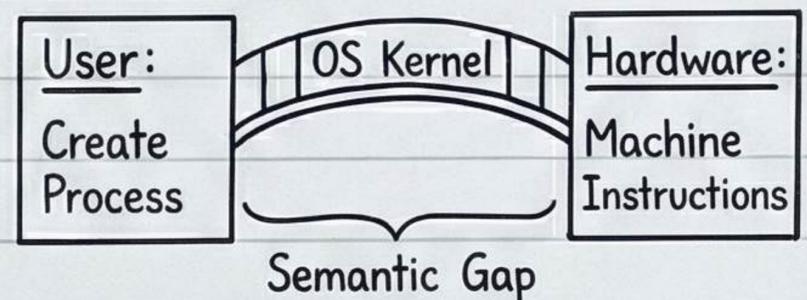
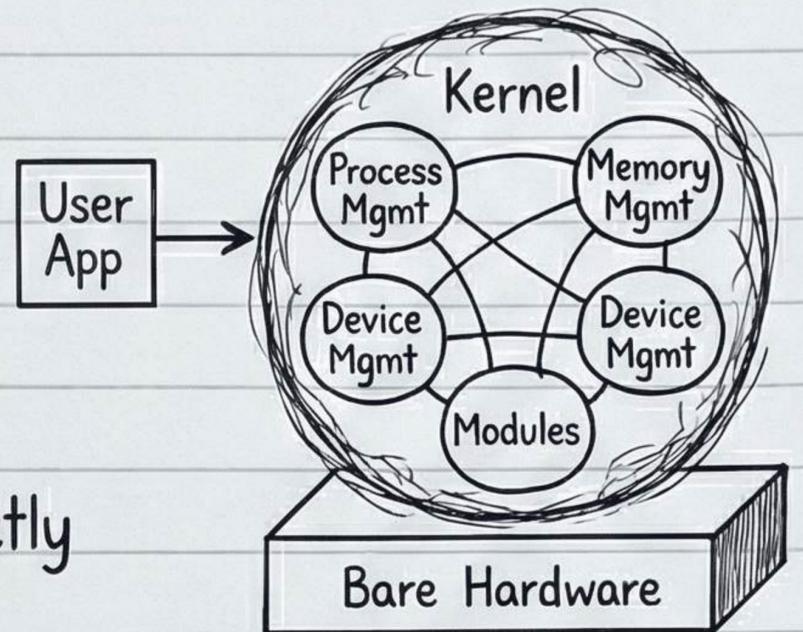
- Difference:** A system call **enters the kernel,** a normal function call does not.



Monolithic Structure of an OS

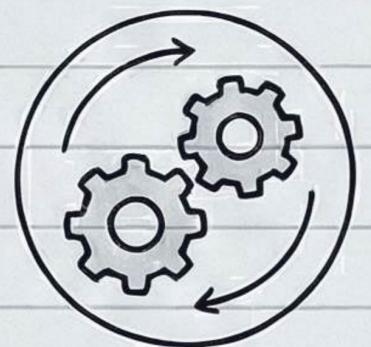
Origin & Structure

- Initial, unplanned architecture where all functionalities were added in the kernel only.
- User applications interact with this single kernel layer, which directly accesses bare hardware.
- Helps bridge the large semantic gap between user operations and machine instructions.



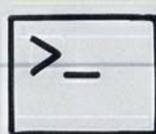
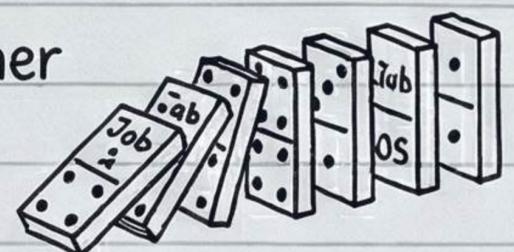
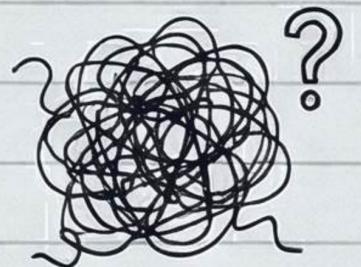
Advantage

- Efficient intercommunication between modules as they are all in the kernel together.



Disadvantages

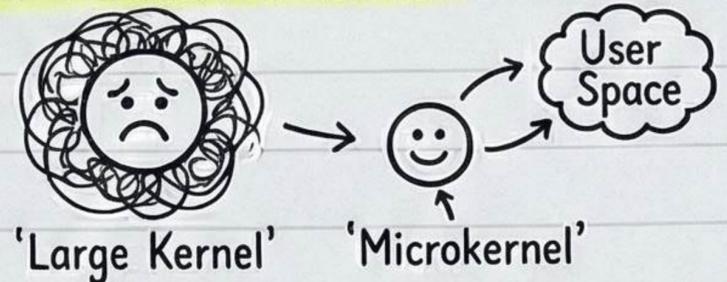
- Difficult to do modifications because a change in one module can affect many others.
- Consequently, debugging... became a difficult job.
- No protection : There is unrestricted access, creating a danger of malicious code.
- Instability : Any user's job can corrupt any other user's job and even OS.
- Examples: DOS, initial UNIX, Linux.



Microkernel Structure of an OS

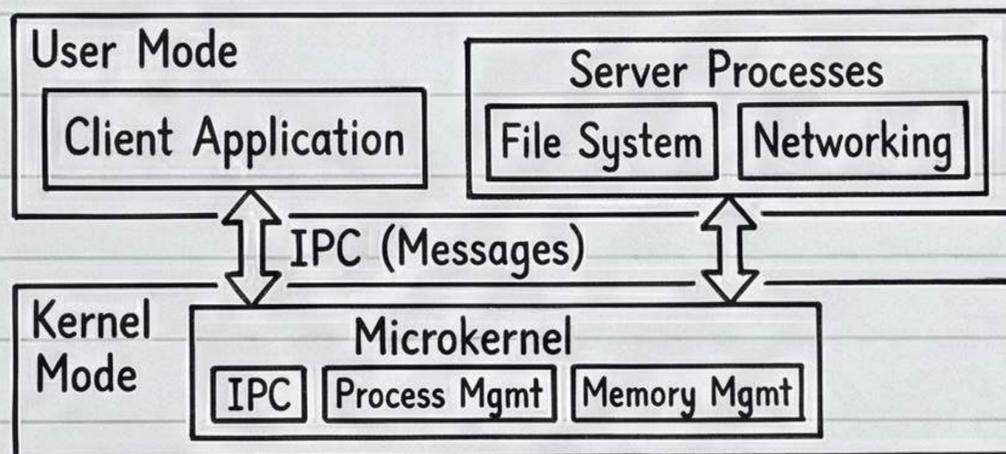
Origin & Need

- As OS demands increased, monolithic/layered kernels grew large and became difficult to manage, extend, and rely on.
- Large kernels were prone to errors and had performance issues.
- Large kernels were prone to errors and had performance issues.
- Adding/deleting support for new devices was hard due to dependencies.



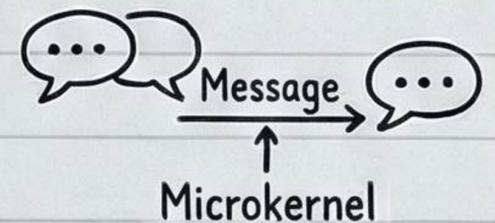
Core Concept & Structure

- The kernel is minimized to only essential functionalities (the 'essential core') like process management, IPC, low-level memory management.
- Non-essential modules are moved to user space as server processes.
- Also known as client-server architecture. cite



Communication (IPC)

- Communication between clients and servers is through message passing, called Inter-process Communication (IPC).
- The microkernel facilitates IPC by validating and passing messages.



Advantages & Examples

- **Adaptable/Extensible** : Easily add/remove modules (e.g., networking) by starting/stopping servers without recompiling the kernel.
- **Reliable/Robust** : If a server module fails, it can be stopped without crashing the entire OS.
- **Examples** : Mach (first & successful), PARAS (C-DAC, India).
- **Difficulty** : Deciding what goes into the essential core.

