



Operating System

Module-3 Notes

by pyqfort.com



Contents Covered:

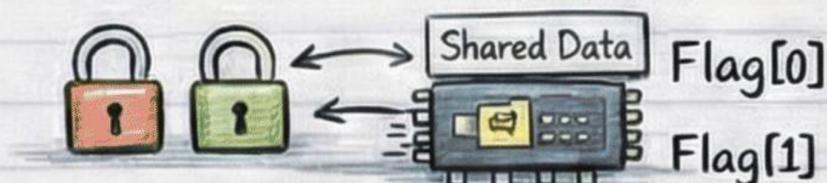
- Intro



- Race Conditions



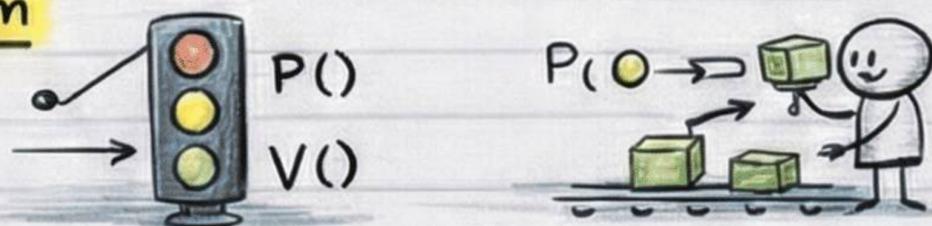
- Mutual Exclusion & Hardware Solution



- Peterson's Solution



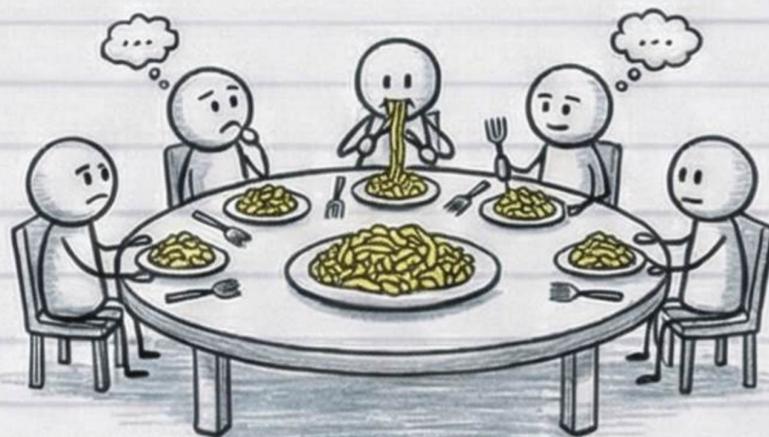
- Producer/Consumer Problem



- Semaphores

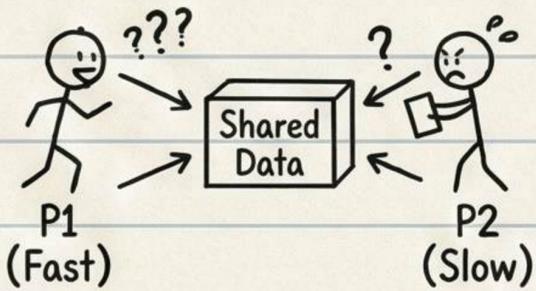
- Monitors

- Dining Philosophers Problem



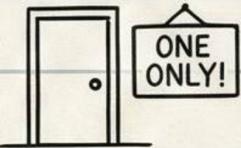
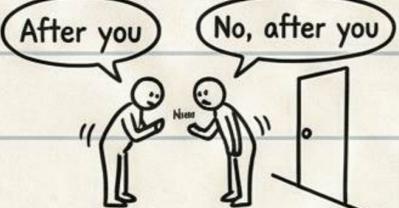
MODULE 3: INTER-PROCESS COMMUNICATION (IPC)

1. The Problem: Concurrency & Shared Data



Concurrency (running at same time, different speeds) + **Shared Data** = Potential **Race Condition** (Outcome depends on timing!)

2. Key Concepts & Definitions

Term	Meaning
Mutual Exclusion	Only ONE process in its Critical Section at a time. 
Critical Section (CS)	Code part accessing/modifying shared resources. MUST BE PROTECTED! 
Livelock	Processes repeatedly yielding to each other, no progress. 

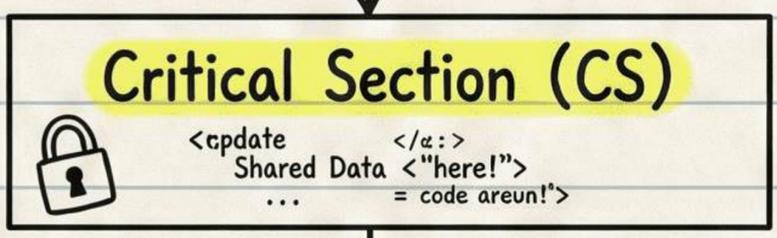
3. The Critical Section Protocol (The Structure)

PROCESS P () {

do {



Check conditions. Stop if busy!



Access/Update Shared Data (Only one here!)



Signal: I'm done! Next process can enter.

... Remainder Section ...

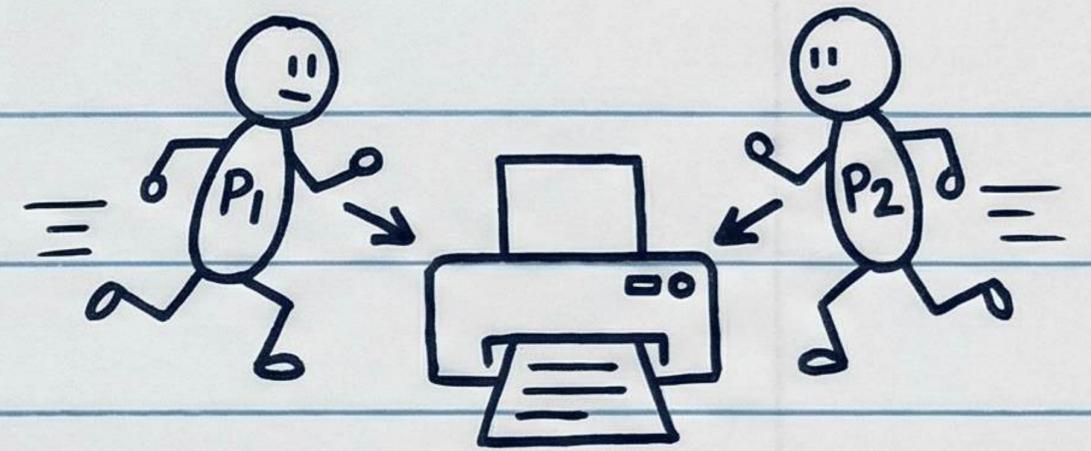
} while (true);

}

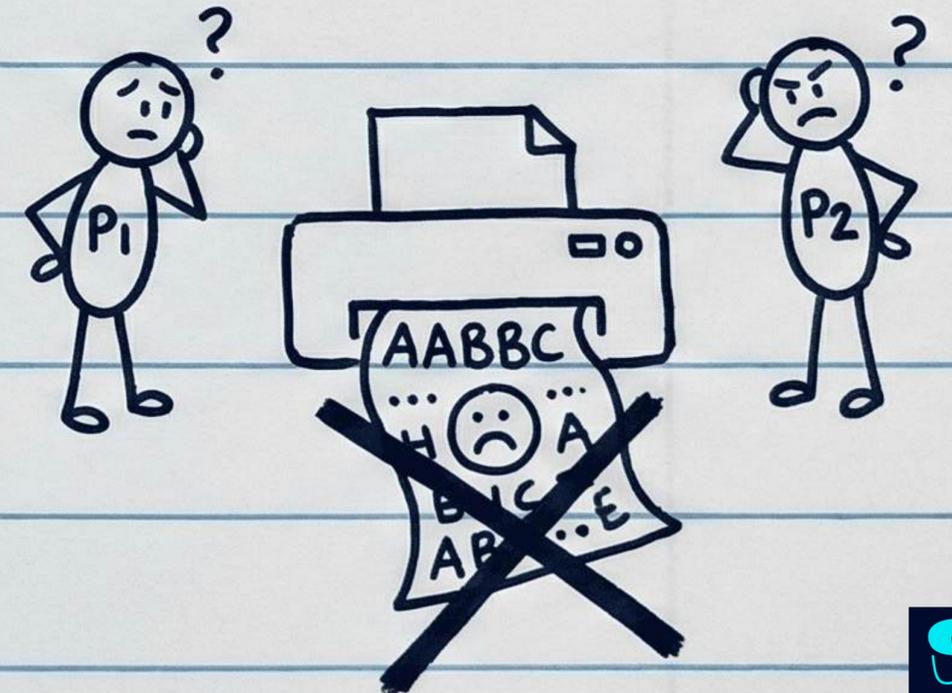


Race Conditions

This happens when two (or more) processes try to access a **non-shareable resource** (like a printer) **at the same time**.



The problem is that the output from the processes gets **mixed up**, and no process gets the **desired result**.

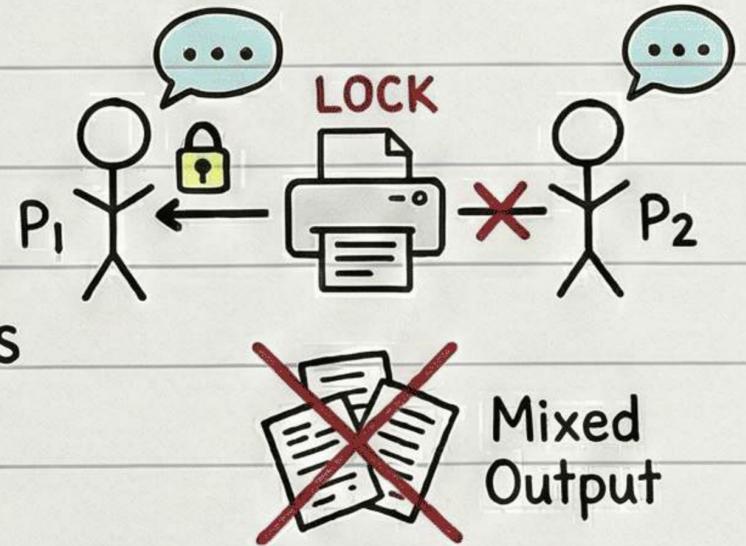


Mutual Exclusion & Hardware Solution

Mutual Exclusion

When a process accesses a **non-shareable resource** (e.g., printer), others must be excluded to prevent mixed output.

This is **Mutual Exclusion**.



It ensures processes do not access a resource **concurrently**.

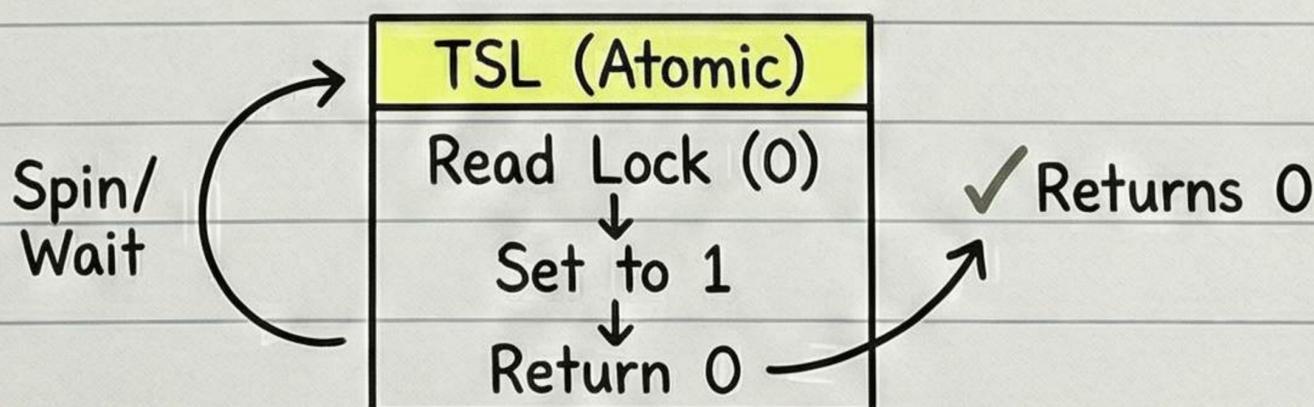
Hardware Solution (Test-and-Set / TSL)

The "Test and Set" (TSL) is a special **atomic hardware instruction** to solve the **critical section problem**.

It works as a single, indivisible operation.

Steps:

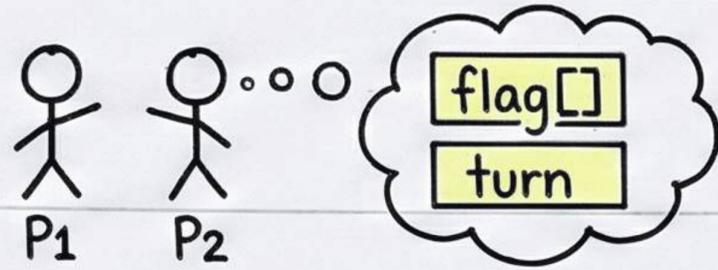
1. **Reads** lock value (e.g., 0 for unlocked).
2. **Sets** lock to 1 (locked) regardless.
3. **Returns** original value read.



Process repeats TSL until it returns 0 (acquired lock).

Atomicity prevents simultaneous access.

Strict Alternation: Peterson's Solution



A software solution for mutual exclusion between two processes using two shared variables.

Process P1

```
do {  
  process_flag[0] = true; // I want in! 🧑  
  process_turn = 1; // Your turn (polite) 🧑→🧑  
  
  while (process_flag[1] && process_turn == 1); 🏠🕒  
  // Wait...  
  
  // Critical Section 🗝️ CS  
  
  process_flag[0] = false; // I'm done! 🧑  
  ...  
} while (true);
```

Process P2

```
do {  
  process_flag[1] = true; // I want in! 🧑  
  process_turn = 0; // Your turn (polite) 🧑←🧑  
  
  while (process_flag[0] && process_turn == 0); 🏠🕒  
  // Wait...  
  
  // Critical Section 🗝️ CS  
  
  process_flag[1] = false; // I'm done! 🧑  
  ...  
} while (true);
```

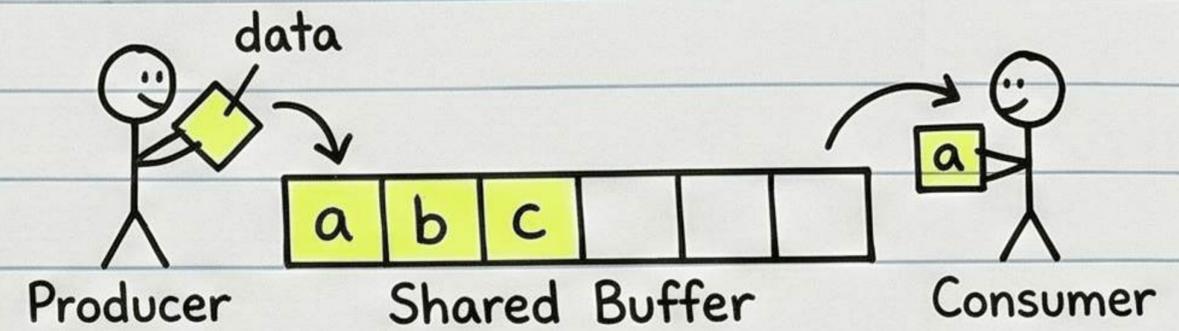
 Summary: Ensures Mutual Exclusion, Progress, and Bounded Waiting. A fair & correct solution!

Checklist: Understand 'flag' & 'turn'? How the 'while' loop works?



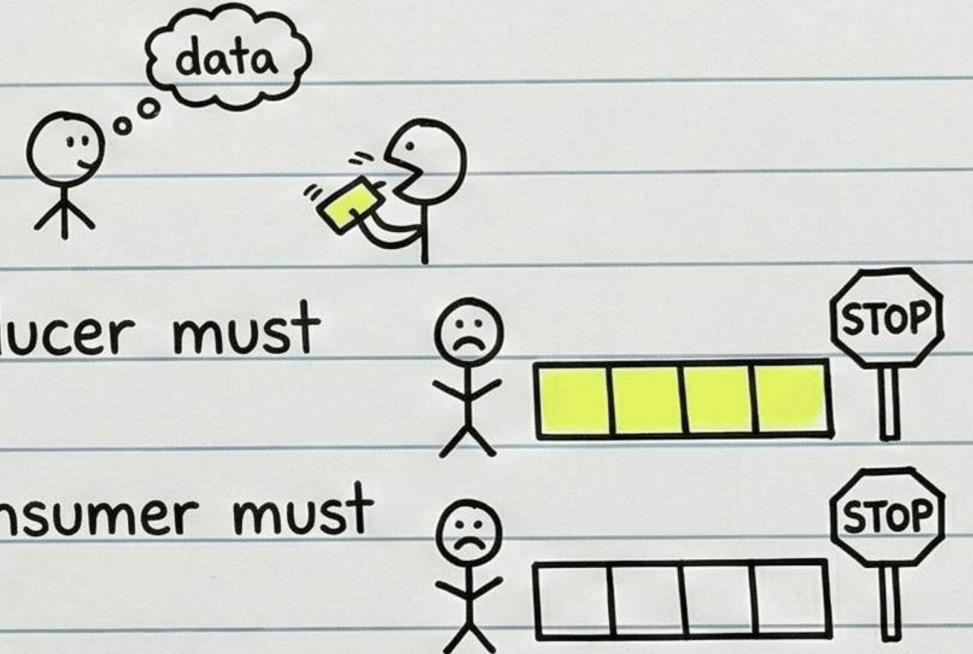
The Producer/Consumer Problem

This is a classic synchronization problem with two processes: a **Producer** and a **Consumer**, who share a **fixed-size buffer**.



How it Works & The Rules

- The **Producer** generates data and puts it into the **buffer**.
- The **Consumer** takes data out of the **buffer** and uses it.
- **Crucial Rule 1 (Producer)**: If the buffer is **FULL**, the Producer must **WAIT** until a slot becomes empty.
- **Crucial Rule 2 (Consumer)**: If the buffer is **EMPTY**, the Consumer must **WAIT** until data is added.



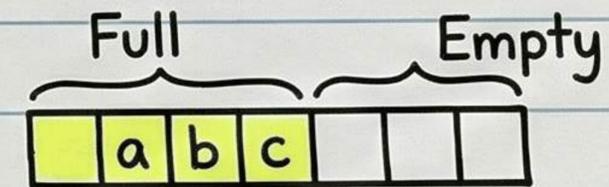
Key Terms & State

Buffer: A temporary storage area (like a queue).

Full: Number of slots containing data.

Empty: Number of free slots.

Goal: We need a way to **synchronize** them so they don't overwrite data or try to consume nothing!



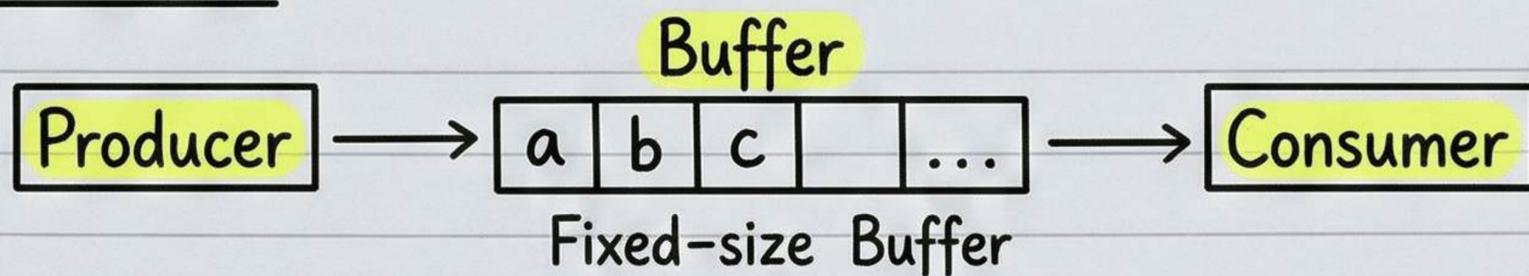
"Full = 3" (items a, b, c)

"Empty = n - 3" (where n is total slots)



The Producer/Consumer Problem Codes

The Problem



Producer creates items, adds to buffer. Consumer removes items. Must synchronize to avoid overflow/underflow & ensure mutual exclusion.

The Solution (Semaphores)

Uses three semaphores:

1. Empty: Count of empty slots (init. N). 

2. Full: Count of filled slots (init. 0). 

3. Buffer_access: Mutex for buffer (init. 1). 

```
Producer() {
  do {
    Produce an item;
    P(Empty); // Wait for slot
    P(Buffer_access); // Lock buffer 
    Add item to buffer;
    V(Buffer_access); // Unlock 
    V(Full); // Signal full
  } while(true);
}
```

```
Consumer() {
  do {
    P(Full); // Wait for item
    P(Buffer_access); // Lock buffer
    Consume item from buffer;
    V(Buffer_access); // Unlock
    V(Empty); // Signal empty
  } while(true);
}
```

P() is wait (decrement). V() is signal (increment). Ensures only one accesses buffer at a time.

Semaphores

A semaphore is a tool for process synchronization. It acts like a guard or lock on a shared resource, preventing race conditions.



Types of Semaphores

Binary Semaphore: Value is only 0 or 1. Used for mutual exclusion of a single resource.

0/1



Counting Semaphore: Can have any positive integer value. Used when there are multiple instances of a resource (e.g., 3 printers → starts at 3).



3 resources

Mutex: A special binary semaphore where only the process that locked it can unlock it.

Operations (Atomic!)

Two indivisible operations:

wait (P): Checks the value. If > 0 , it decrements and proceeds. If ≤ 0 , it waits.



signal (V): Increments the value, potentially allowing a waiting process to enter.



Implementation: Busy Waiting vs. Blocking

Problem: A simple $\text{while}(S \leq 0)$; loop creates busy waiting or a spinlock, which wastes CPU time.



Solution: Instead of spinning, the process should be blocked and put into a waiting queue.

A signal operation then wakes up a process from the queue.



Queue (Zzz...)

This uses a structure: `struct { int value; queue q; }`



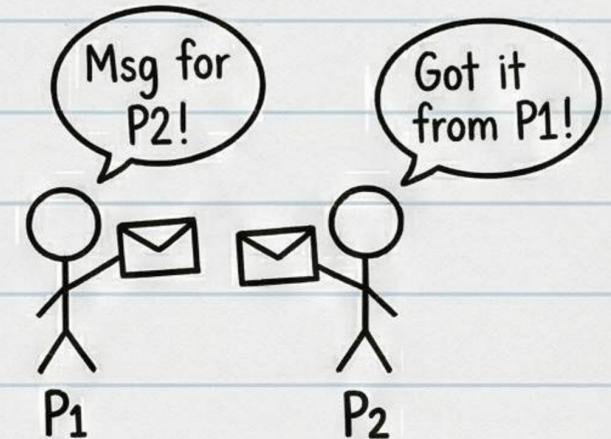
Monitors: Message Passing

Process communication can happen in three ways: shared memory, message passing, and signals.



Message Passing

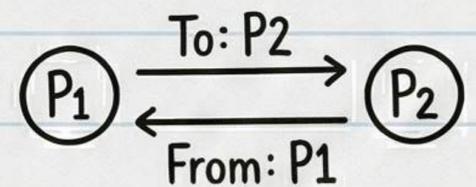
Processes communicate by sending messages and are explicitly aware of each other.



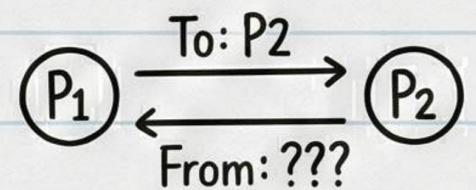
Direct Addressing

Processes must know each other's names.

- Symmetric: Both sender & receiver know each other's names.

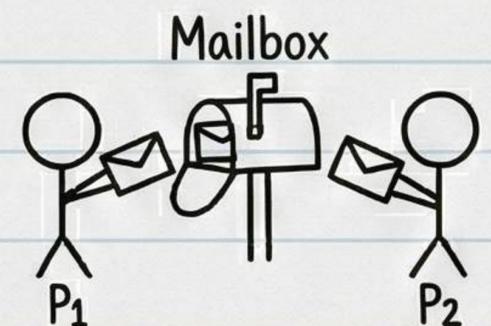


- Asymmetric: Sender knows receiver's name, but receiver doesn't know sender's.



Indirect Addressing

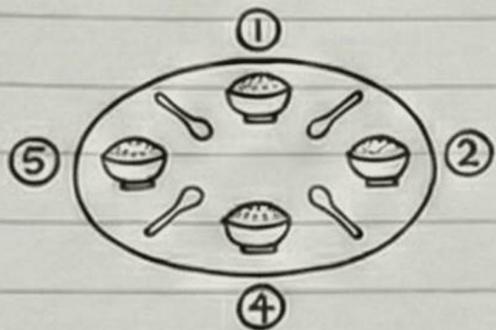
Processes use a shared mailbox to store messages. They don't need to know each other's names directly.



- Link types: One-to-one, one-to-many, many-to-one, many-to-many

NOTE: Each philosopher needs both adjacent spoons simultaneously to eat — one from left and one from right neighbor.

Dining Philosophers Problem (Dijkstra): Classic synchronization IPC problem. Five philosophers around a round table, think & eat. Infinite rice, but only 5 spoons, one between each pair. Need 2 spoons to eat.



Deadlock: If all pick up left spoon simultaneously.

Livelock: All put down & retry simultaneously. System won't progress.

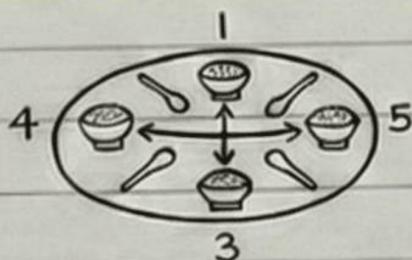
SOLUTIONS:

1. **Limit Philosophers**: Allow only 4 to sit. Fifth prevented from sitting. Deadlock avoided.

Algorithm (Semaphore):

```
do {  
    wait (Sem_Philosopher);  
    wait (Sem_Spoon[n]);  
    wait (Sem_Spoon[(n+1)%5]);  
    eat();  
    signal (Sem_Spoon[n]);  
    signal (Sem_Spoon[(n+1)%5]);  
    signal (Sem_Philosopher);  
    think();  
} while (true);
```

2. **Asymmetric Solution**: Odd-numbered pick left first, then right. Even-numbered pick right first, then left.



Odd can pick up left. Even cannot pick up right. Philosophers 1 & 3 can eat.

```
do {  
    if (n%2 != 0) {  
        wait (Sem_Spoon[n]);  
        wait (Sem_Spoon[(n+1)%5]);  
        eat();  
    } else {  
        wait (Sem_Spoon[(n+1)%5]);  
        wait (Sem_Spoon[n]);  
        eat();  
    }  
    think();  
} while (true);
```

Conditions: One philosopher per spoon. No deadlock. No starvation. Max concurrent eating.

